House File 535

H-1202

- 1 Amend House File 535 as follows:
- 2 1. By striking everything after the enacting clause and
- 3 inserting:
- 4 <Section 1. NEW SECTION. 321.514 Definitions.
- 5 As used in this section and sections 321.515 through
- 6 321.519, unless the context otherwise requires:
- 7 1. "Automated driving system" means the hardware and
- 8 software collectively capable of performing all dynamic driving
- 9 tasks on a sustained basis, regardless of whether the system is
- 10 limited to a specific operational design domain, if any.
- 11 2. "Conventional human driver" means a natural person
- 12 who manually controls the in-vehicle accelerating, braking,
- 13 steering, and transmission gear selection input devices in
- 14 order to operate a motor vehicle.
- 3. "Driverless-capable vehicle" means a system-equipped
- 16 vehicle capable of performing all dynamic driving tasks within
- 17 the automated driving system's operational design domain, if
- 18 any, including but not limited to achievement of a minimal risk
- 19 condition without intervention or supervision by a conventional
- 20 human driver.
- 21 4. "Dynamic driving task" means any real-time operational
- 22 and tactical function required to operate a motor vehicle on
- 23 a highway in traffic within an automated driving system's
- 24 specific operational design domain, if any. "Dynamic driving
- 25 task" does not include any strategic function such as trip
- 26 scheduling or the selection of destinations and waypoints.
- 27 5. "Minimal risk condition" means a reasonably safe state
- 28 to which an automated driving system brings a system-equipped
- 29 vehicle upon experiencing a performance-relevant failure of the
- 30 system that renders the system unable to perform any dynamic
- 31 driving task, including but not limited to removing the vehicle
- 32 to the nearest shoulder if the vehicle is capable of doing so,
- 33 bringing the vehicle to a complete stop, and activating the
- 34 vehicle's emergency signal lamps.
- 35 6. "On-demand driverless-capable vehicle network" means a

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- 1 transportation service network that uses a software application
- 2 or other digital means to dispatch driverless-capable vehicles
- 3 for the purposes of transporting persons or goods, including
- 4 transportation for hire as defined in section 325A.1, and
- 5 public transportation.
- 6 7. "Operational design domain" means a set of constraints
- 7 used to define the domain under which an automated driving
- 8 system is designed to properly operate, including but not
- 9 limited to types of highways, speed ranges, environmental
- 10 conditions such as weather or time of day, and other
- ll constraints.
- 12 8. "System-equipped vehicle" means a motor vehicle equipped
- 13 with an automated driving system.
- 14 Sec. 2. NEW SECTION. 321.515 Operation.
- 15 l. A driverless-capable vehicle may operate on the public
- 16 highways of this state without a conventional human driver
- 17 physically present in the vehicle, if the vehicle meets all of
- 18 the following conditions:
- 19 a. The vehicle is capable of achieving a minimal risk
- 20 condition if a malfunction of the automated driving system
- 21 occurs that renders the system unable to perform any dynamic
- 22 driving task within the system's intended operational design
- 23 domain, if any.
- 24 b. While in driverless operation, the vehicle is capable of
- 25 operating in compliance with the applicable traffic and motor
- 26 vehicle safety laws and regulations of this state that govern
- 27 the performance of dynamic driving tasks, unless an exemption
- 28 has been granted to the vehicle by the department.
- 29 c. The vehicle has been certified by the vehicle's
- 30 manufacturer to be in compliance with all applicable federal
- 31 motor vehicle safety standards, except to the extent an
- 32 exemption has been granted for the vehicle under applicable
- 33 federal law or by the national highway traffic safety
- 34 administration.
- 35 2. a. The operation of a system-equipped vehicle capable

- 1 of performing all dynamic driving tasks within the automated
- 2 driving system's operational design domain on the public
- 3 highways of this state while a conventional human driver is
- 4 present in the vehicle shall be lawful. During such operation,
- 5 the conventional human driver shall possess a valid driver's
- 6 license pursuant to section 321.174. The conventional human
- 7 driver shall operate the system-equipped vehicle according
- 8 to the manufacturer's requirements and specifications, and
- 9 shall regain manual control of the vehicle when prompted by the
- 10 automated driving system.
- ll b. An automated driving system, while engaged, shall be
- 12 designed to operate within the system's operational design
- 13 domain in compliance with the applicable traffic and motor
- 14 vehicle safety laws and regulations of this state that govern
- 15 the performance of dynamic driving tasks, unless an exemption
- 16 has been granted to the vehicle by the department.
- 3. Except as provided in this section, the motor vehicle
- 18 laws of this state shall not be construed to require a
- 19 conventional human driver to operate a driverless-capable
- 20 vehicle that is being operated by an automated driving system.
- 21 The automated driving system, while engaged, shall be deemed
- 22 to fulfill any physical acts required of a conventional human
- 23 driver to perform dynamic driving tasks.
- 24 Sec. 3. NEW SECTION. 321.516 Insurance.
- 25 Before a system-equipped vehicle is allowed to operate on
- 26 the public highways of this state, the owner shall submit to
- 27 the department proof of financial liability coverage for the
- 28 vehicle in a manner and form determined by the department. A
- 29 system-equipped vehicle shall not operate on the highways of
- 30 this state unless financial liability coverage is in effect for
- 31 the vehicle and unless proof of financial liability coverage is
- 32 carried in the vehicle. If a system-equipped vehicle operates
- 33 on a highway in violation of this section, the owner of the
- 34 vehicle may be charged and convicted of a violation of section
- 35 321.20B as though the owner was operating the vehicle.

- 1 Sec. 4. NEW SECTION. 321.517 Accidents.
- In the event of an accident in which a system-equipped
- 3 vehicle is involved, the vehicle shall remain at the scene of
- 4 the accident and the operation of the vehicle shall otherwise
- 5 comply with sections 321.261 through 321.273 where applicable
- 6 and to the extent possible, and the vehicle's owner or a person
- 7 on behalf of the vehicle's owner shall promptly report the
- 8 accident to law enforcement authorities. If a system-equipped
- 9 vehicle fails to remain at the scene of an accident or the
- 10 operation of the vehicle fails to otherwise comply with
- 11 sections 321.261 through 321.273 where applicable and to the
- 12 extent possible as required by this section, the vehicle's
- 13 failure shall be imputed to the vehicle's owner, and the
- 14 vehicle's owner may be charged and convicted of a violation of
- 15 sections 321.261 through 321.273, as applicable. However, if
- 16 the vehicle's failure is due to an error or malfunction in the
- 17 automated driving system, the vehicle's failure shall instead
- 18 be imputed to the vehicle's manufacturer, and the vehicle's
- 19 manufacturer may be charged and convicted for a violation of
- 20 sections 321.261 through 321.373, as applicable.
- 21 Sec. 5. NEW SECTION. 321.518 On-demand driverless-capable
- 22 vehicle network.
- 23 A person may operate an on-demand driverless-capable vehicle
- 24 network. An on-demand driverless-capable vehicle network may
- 25 be used to facilitate the transportation of persons or goods,
- 26 including transportation for hire as defined in section 325A.1,
- 27 and public transportation. An on-demand driverless-capable
- 28 vehicle network may connect passengers to driverless-capable
- 29 vehicles either exclusively or as part of a digital network
- 30 that also connects passengers to conventional human drivers
- 31 who provide transportation services, consistent with chapter
- 32 321N or any other applicable laws, in vehicles that are not
- 33 driverless-capable vehicles.
- 34 Sec. 6. NEW SECTION. 321.519 Authority.
- 35 1. Automated driving systems and system-equipped vehicles

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- 1 shall be governed by sections 321.514 through 321.518, this
- 2 section, and all applicable traffic and motor vehicle safety
- 3 laws and regulations of this state. Automated driving systems
- 4 and system-equipped vehicles shall be regulated exclusively by
- 5 the department. The department may adopt rules pursuant to
- 6 chapter 17A to administer sections 321.514 through 321.518, and
- 7 this section.
- 8 2. A political subdivision of the state shall not impose
- 9 requirements, including but not limited to performance
- 10 standards, specific to the operation of system-equipped
- 11 vehicles, automated driving systems, or on-demand
- 12 driverless-capable vehicle networks that are in addition to
- 13 the requirements set forth under sections 321.514 through
- 14 321.518. A political subdivision of the state shall not
- 15 impose a tax on system-equipped vehicles, automated driving
- 16 systems, or on-demand driverless-capable vehicle networks
- 17 where such tax relates specifically to the operation of
- 18 system-equipped vehicles, automated driving systems, or
- 19 on-demand driverless-capable vehicle networks.>

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